

On the Geometry of Moduli Space of Vacua in N=2 Supersymmetric Yang–Mills Theory *

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Abstract

We consider generic properties of the moduli space of vacua in $N = 2$ supersymmetric Yang–Mills theory recently studied by Seiberg and Witten. We find, on general grounds, Picard–Fuchs type of differential equations expressing the existence of a flat holomorphic connection, which for one parameter (*i.e.* for gauge group $G = SU(2)$), are second order equations. In the case of coupling to gravity (as in string theory), where also “gravitational” electric and magnetic monopoles are present, the electric–magnetic S duality, due to quantum corrections, does not seem any longer to be related to $Sl(2, \mathbb{Z})$ as for $N = 4$ supersymmetric theory.

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Recently it has been shown that general properties of electric-magnetic duality, which is eventually linked to a conjectured dilaton-axion duality in superstring theories[1], can be described in a fairly general way in $N = 4$ [2] and $N = 2$ [3] supersymmetric Yang-Mills theories. However, $N = 2$ Yang-Mills theories look much more interesting since both perturbative and non perturbative phenomena, absent for $N = 4$ [4], play an important rôle in the discussion and determination of the electric-magnetic duality. Due to the fact that the moduli space of $N = 2$ Yang-Mills vacua is given by an $N = 2$ Kählerian space of a particular kind[5], it turns out that electric-magnetic duality is described by a monodromy group Γ which is a subgroup of $Sp(2r, \mathbb{Z})$ where r is the rank of the Yang-Mills group G . For the case $r = 1$ ($G = SU(2)$), Seiberg and Witten identified Γ to be the group $\Gamma_2 \subset Sp(2, \mathbb{Z}) \simeq Sl(2, \mathbb{Z})$ [3]. The monodromies are reminiscent of a similar problem that arises in the analysis of Calabi-Yau moduli space[6] where the monodromy group Γ , related to the target space duality group[7], is a discrete subgroup of $Sp(2h_{21} + 2, \mathbb{Z})$ and is related to the three-form cohomology.

In this paper we show that, as expected, the monodromy related to electric-magnetic duality arises from “Picard-Fuchs” equations[8] which are associated to the rigid special geometry of $N = 2$ supersymmetric Yang-Mills theories. Following lines similar to those concerning the special geometry of Calabi-Yau moduli space[5], we shall first give a résumé of “rigid special geometry” in a coordinate free way and then write the associated system of differential equations, which always can be interpreted as the existence of a flat holomorphic connection on a certain holomorphic bundle.

Let us first remind that if one has n abelian vector multiplets (here $n = r$ since we consider generic flat directions of a pure Yang-Mills theory with gauge group G broken to $U(1)^r$) their scalar fields, in a supergravity basis, describe a Kählerian sigma model

$$G_{A\bar{B}} \partial X^A \partial \bar{X}^{\bar{B}} \quad (1)$$

with metric

$$G_{A\bar{B}} = -2 \operatorname{Im} \partial_A \partial_{\bar{B}} F = \partial_A \partial_{\bar{B}} i (F_C \bar{X}^{\bar{C}} - \bar{F}_{\bar{C}} X^C) \quad (2)$$

where F is a holomorphic function of X ($\bar{\partial} F = 0$). These coordinates are the analogue of the “special coordinates” in the context of Calabi-Yau moduli space. A general coordinate free way of describing the special geometry for that case was given in [5] and the associated system of Picard-Fuchs equations, together with the

flat holomorphic geometry, was discussed in [5,8] . The Riemann tensor of special geometry satisfies

$$R_{\alpha\bar{\beta}\gamma\bar{\delta}} = g_{\alpha\bar{\beta}}g_{\gamma\bar{\delta}} + g_{\gamma\bar{\beta}}g_{\alpha\bar{\delta}} - e^{2K}W_{\alpha\beta\epsilon}W_{\bar{\beta}\bar{\delta}\bar{\epsilon}}G^{\epsilon\bar{\epsilon}} , \quad (3)$$

where $G_{\epsilon\bar{\epsilon}} = \partial_{\epsilon}\partial_{\bar{\epsilon}}K$ is the Kähler metric and $W_{\alpha\beta\gamma}$ is a totally symmetric holomorphic tensor.

Here we consider rigid special geometry, where the moduli space is simply a Kähler rather than a Kähler -Hodge manifold, and the constraint (3) becomes

$$R_{\alpha\bar{\beta}\gamma\bar{\delta}} = -W_{\alpha\beta\epsilon}W_{\bar{\beta}\bar{\delta}\bar{\epsilon}}G^{\epsilon\bar{\epsilon}} . \quad (4)$$

In the X coordinates $G_{\epsilon\bar{\epsilon}}$ is given by eq. (2) and

$$W_{ABC} = \partial_A\partial_B\partial_C F . \quad (5)$$

To promote formulae (2), (5) to arbitrary coordinates, one introduces n holomorphic functions $X^A(z)$ and a function $F(X^A(z))$. Then the Kähler potential is

$$K(z, \bar{z}) = i(F_A \bar{X}^A - \bar{F}_A X^A) \quad (F_A = \frac{\partial F}{\partial X^A}) , \quad (6)$$

and

$$\begin{aligned} G_{\alpha\bar{\beta}} &= \partial_{\alpha}X^A\partial_{\bar{\beta}}\bar{X}^B\frac{\partial}{\partial X^A}\frac{\partial}{\partial \bar{X}^B}K \\ W_{\alpha\beta\gamma} &= \partial_{\alpha}X^A\partial_{\beta}X^B\partial_{\gamma}X^C\partial_A\partial_B\partial_C F \end{aligned} \quad (7)$$

It is convenient, as in ref. [5,8], to introduce the flat vielbein

$$e_{\alpha}^A = \partial_{\alpha}X^A \quad (8)$$

which is a $n \times n$ matrix. The Christoffel connection $\Gamma_{\alpha\beta}^{\gamma}$ whose Riemann tensor satisfies

$$\partial_{\bar{\gamma}}\Gamma_{\alpha\beta}^{\delta} = G^{\delta\bar{\delta}}R_{\alpha\bar{\gamma}\beta\bar{\delta}} = -W_{\alpha\beta\epsilon}\bar{W}_{\bar{\gamma}\bar{\delta}\bar{\epsilon}}G^{\epsilon\bar{\epsilon}}G^{\delta\bar{\delta}} \quad (9)$$

can be written as

$$\Gamma_{\alpha\beta}^{\delta}(z, \bar{z}) = T_{\alpha\beta}^{\delta}(z, \bar{z}) + \hat{\Gamma}_{\alpha\beta}^{\delta}(z) , \quad (10)$$

where

$$\begin{aligned} T_{\alpha\beta}^{\delta}(z, \bar{z}) &= e_{\alpha}^A e_{\beta}^B \partial_B G_{A\bar{D}} G^{-1\bar{D}C} e_C^{-1\delta} \\ \hat{\Gamma}_{\alpha\beta}^{\delta}(z) &= \partial_{\beta} e_{\alpha}^A e_A^{-1\delta} \end{aligned} \quad (11)$$

From (11) eq. (9) immediately follows. $\widehat{\Gamma}$ defines a flat connection in an $n \times n$ space: $R(\widehat{\Gamma}) = 0$.

If one introduces the $2n$ objects $X^A(z), F_A(z)$ and the $2n$ dimensional vector $V = (X^A, F_A)$, it is easy to show that the following identities hold

$$\begin{aligned} D_\alpha V &= V_\alpha \\ D_\alpha V_\beta &= -i W_{\alpha\beta\gamma} V^\gamma \quad V^\gamma = G^{\gamma\bar{\gamma}} \bar{V}_{\bar{\gamma}} \\ D_\alpha \bar{V}_{\bar{\gamma}} &= 0 \end{aligned} \tag{12}$$

where D_α is the covariant derivative in the original Kähler manifold. To this non holomorphic system of identities it is associated an holomorphic system, which is obtained by replacing D_α with the flat covariant derivative \widehat{D}_α where $\Gamma \rightarrow \widehat{\Gamma}$, and V^γ is replaced by a holomorphic vector

$$V^\alpha = (0, e^{-1\alpha}_A) . \tag{13}$$

Since the first equation is left invariant by constant translations $V \rightarrow V + c$, it is actually possible to consider (V, V_α, V^α) as $(2N + 1)$ vectors so that

$$\begin{aligned} V &= (1, X^A, F_A) \\ V_\alpha &= (0, e_\alpha^A, e_\alpha^B F_{AB}) \\ V^\alpha &= (0, 0, e^{-1\alpha}_A) \end{aligned} \tag{14}$$

In terms of the $(2n + 1) \times (2n + 1)$ matrix

$$\mathcal{V} = \begin{pmatrix} V \\ V_\beta \\ V^\beta \end{pmatrix} , \tag{15}$$

the holomorphic system can be written as

$$\mathcal{D}_\alpha \mathcal{V} = 0 , \tag{16}$$

with

$$\mathcal{D}_\alpha = \partial_\alpha - \mathcal{A}_\alpha \tag{17}$$

and the flat connection \mathcal{A}_α given by

$$\mathcal{A}_\alpha = \begin{pmatrix} 0 & \delta_\alpha^\gamma & 0 \\ 0 & \widehat{\Gamma}_{\alpha\beta}^\gamma & (W_\alpha)_{\beta\gamma} \\ 0 & 0 & -\widehat{\Gamma}_{\alpha\gamma}^\beta \end{pmatrix} . \tag{18}$$

Note that there is a $ISp(2n)$ acting on the right hand side of V (or \mathcal{V}) represented as $\begin{pmatrix} 1 & 0 \\ C & M \end{pmatrix}$ with $M \subset Sp(2n)$. This follows from the fact that the submatrix $\begin{pmatrix} \hat{\Gamma}_{\alpha\beta}^\gamma & (W_\alpha)_{\beta\gamma} \\ 0 & -\hat{\Gamma}_{\alpha\gamma}^\beta \end{pmatrix}$ is valued in the lie algebra of $Sp(2n)$ (with respect to the metric $Q = \begin{pmatrix} 0 & -1_n \\ 1_n & 0 \end{pmatrix}$).

In special coordinates $e_\alpha^A = \delta_\alpha^A$, $\hat{\Gamma} = 0$ and the connection \mathcal{A}_α reduces to

$$\mathcal{A}_\alpha = \begin{pmatrix} 0 & \delta_\alpha^\gamma & 0 \\ 0 & 0 & W_{\alpha\beta\gamma} \\ 0 & 0 & 0 \end{pmatrix} \quad (19)$$

which is nilpotent of degree three ($(\mathcal{A}_\alpha)^3 = 0$).

Eq. (16) can be rewritten as a system of third order differential equations for the upper component of \mathcal{V} ,

$$\hat{D}_\alpha (W^{-1\hat{\gamma}})^{\epsilon\beta} \hat{D}_{\hat{\gamma}} \partial_\beta V = 0, \quad (20)$$

(where $\hat{\gamma}$ is a priori not summed over). Actually, since the first equation in (12) can be used to just start with V_α , (20) can be reduced to a second order differential equation for $V_\beta = \partial_\beta V$. We can then delete the first entry in (14)

$$\begin{aligned} V_\alpha &= (e_\alpha^A, e_\alpha^B F_{AB}) \\ V^\alpha &= (0, e_A^{-1\alpha}) \end{aligned} \quad (21)$$

and write the connection as $\mathcal{A}_\alpha = \begin{pmatrix} \hat{\Gamma}_{\alpha\beta}^\gamma & (W_\alpha)_{\beta\gamma} \\ 0 & -\hat{\Gamma}_{\alpha\gamma}^\beta \end{pmatrix}$, which reduces in special coordinates to

$$\mathcal{A}_\alpha = \begin{pmatrix} 0 & (W_\alpha)_{\beta\gamma} \\ 0 & 0 \end{pmatrix} \quad (22)$$

which is then nilpotent of degree two, and $W_{\alpha\beta\gamma}$ is an n -dimensional abelian subalgebra. The physical meaning of $W_{\alpha\beta\gamma}$ is that they are related to the Riemann tensor over the moduli space by eq. (4).

In the case of one variable ($n = 1$), equation (20) becomes

$$(\hat{D}W^{-1}\hat{D}\hat{\partial})V = 0, \quad (23)$$

and setting $U = \partial V$ it becomes

$$(\partial + \widehat{\Gamma})W^{-1}(\partial - \widehat{\Gamma})U = 0 . \quad (24)$$

This yields a second order equation

$$\partial^2 U + a_1 \partial U + a_0 U = 0 , \quad (25)$$

with

$$\begin{aligned} a_1 &= -\partial \log W \\ a_0 &= \partial \log W \widehat{\Gamma} - \partial \widehat{\Gamma} + \widehat{\Gamma}^2 \quad \widehat{\Gamma} = \partial \log e \end{aligned} \quad (26)$$

so that knowing a_1, a_0 one can compute W and e ($e=1$ in special coordinates). Note that the general solution in the one parameter case is

$$U = \partial V = (e, e \frac{\partial^2 F}{\partial X^2}) , \quad (27)$$

where e is the vielbein component that here plays the rôle of a rescaling factor. Taking the ratio of the two solutions one gets that $\tau = \frac{\partial^2 F}{\partial X^2}$ is the uniformizing variable for which the differential equation reduces to $\frac{d^2}{d\tau^2}(\) = 0$. This is consistent with the fact that the metric of the effective supergravity theory is

$$G_{z\bar{z}} = |e(z)|^2 \text{Im } \tau = |e(z)|^2 \text{Im } \frac{\partial^2 F}{\partial X^2} > 0 \quad (28)$$

and therefore manifestly positive[3].

As an explicit example, let us derive the differential equation (25) for the particular one parameter case of Seiberg and Witten [3]. Consider the family E_u of genus one Riemann surfaces

$$y^2 = (x+1)(x-1)(x-u) , \quad (29)$$

which, in homogeneous coordinates ($x \rightarrow \frac{x}{z}, y \rightarrow \frac{y}{z}$) can be described by the vanishing of the homogeneous polynomial \mathcal{W} in CP^2 ,

$$\mathcal{W}(x, y, z) = -zy^2 + x(x^2 - z^2) - u z(x^2 - z^2) . \quad (30)$$

For convenience, we change variables to ($x \rightarrow x+z, z \rightarrow x-z$), obtaining

$$\mathcal{W} = -(x-z)y^2 + xz(x-z) - u xz(x-z) . \quad (31)$$

The differential equation associated to (31) can now be derived using standard techniques, familiar from topological Landau–Ginzburg theories [9]. Define the integrals

$$U_0 = \int \frac{\omega}{\mathcal{W}} \quad , \quad U_1 \equiv \frac{dU_0}{du} = \int \frac{\omega}{\mathcal{W}^2} xz(x-z) \quad (32)$$

where ω is a volume form, which form a basis of the cohomology $H^1(E_u)$. By differentiating under the integral sign and using the “vanishing relations” $\frac{\partial \mathcal{W}}{\partial x} = \frac{\partial \mathcal{W}}{\partial y} = \frac{\partial \mathcal{W}}{\partial z} = 0$, one can show that the vector $\begin{pmatrix} U_0 \\ U_1 \end{pmatrix}$ satisfies a regular, singular matrix differential equation

$$\frac{d}{du} \begin{pmatrix} U_0 \\ U_1 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ \frac{2u}{(1-u^2)} & \frac{1}{4(1-u^2)} \end{pmatrix} \begin{pmatrix} U_0 \\ U_1 \end{pmatrix} \quad , \quad (33)$$

which is equivalent to the second order differential equation

$$\frac{d^2 U_0}{du^2} - \frac{2u}{(1-u^2)} \frac{dU_0}{du} - \frac{1}{4(1-u^2)} U_0 = 0 \quad . \quad (34)$$

Comparing (34) with (25), (26) one can read out that

$$W = \frac{1}{(u^2 - 1)} \quad (35)$$

and that $\hat{\Gamma}$ satisfies

$$-\frac{2u}{u^2 - 1} \hat{\Gamma} - \partial \hat{\Gamma} + \hat{\Gamma}^2 = \frac{1}{4(u^2 - 1)} \quad . \quad (36)$$

Writing $\hat{\Gamma} = \partial \log e$, then (36) coincides with equation (34) for U_0 , in agreement with the fact that, according to (27), e is one of the solutions of (34).

As a check, we may compute the asymptotic behaviour of the solutions $(U_0^{(1)}, U_0^{(2)})$ of this fuchsian equation around the singular points $u = 1, -1, \infty$. We find

$$\begin{aligned} u \rightarrow \pm 1 & \quad (U_0^{(1)}, U_0^{(2)}) \approx (c_1, \log(u \mp 1)) \\ u \rightarrow \infty & \quad (U_0^{(1)}, U_0^{(2)}) \approx (u^{-1/2}, u^{-1/2} \log u) \end{aligned} \quad . \quad (37)$$

Recalling that $U_0^{(1)} = \partial V^{(1)}, U_0^{(2)} = \partial V^{(2)}$ and the third period $V^{(3)} = c$, one finds

$$\begin{aligned} u \rightarrow \pm 1 & \quad (V^{(1)}, V^{(2)} + V^{(3)}) \approx (u \mp 1, c + c'(u \mp 1) \log(u \mp 1)) \\ u \rightarrow \infty & \quad (V^{(1)}, V^{(2)} + V^{(3)}) \approx (u^{1/2}, u^{1/2} \log u) \end{aligned} \quad (38)$$

in agreement with the behaviour of the periods (a, a_D) of [3].

The change of variables $u \rightarrow 1 - 2z$, puts eq.(34) into the form of an hypergeometric equation of parameters $(\frac{1}{2}, \frac{1}{2}, 1)$ so that $U_0^1 = {}_2F_1[\frac{1}{2}, \frac{1}{2}, 1; \frac{1-u}{2}]$. Using the standard relations among hypergeometric functions [10] one could also reconstruct the monodromy matrices of the periods in a symplectic basis as given in [3].

The geometry of the moduli space is actually remarkably different when gravitational degrees of freedom are introduced [2]. The reason is that in that case there are always two additional $U(1)$ factors, one coming from $G_{\mu i}$ and the other from $B_{\mu i}$. One is the $N = 2$ graviphoton and the other is the vector partner of the dilaton–axion multiplet. Therefore one gets a $U(1)^{r+2}$ abelian algebra and at least $r + 1$ vector multiplets. In string theory with maximal G , $r = 22$ and the special Kähler manifold has dimension $r + 1$. If the gauge group would be taken to be $SU(2)$ ($r = 1$), then the holomorphic prepotential would be of the form [3,4] (in special coordinates $s = \frac{X_1}{X_0}, t = \frac{X_2}{X_0}$, and for instanton number n)

$$F(s, t) = st^2 + f_{one\ loop}(t) + \sum_{n=1}^{\infty} C_n t^2 \left(\frac{\Lambda^2}{t^2}\right)^{2n} e^{2\pi i n s} \quad (39)$$

with $s = i\frac{4\pi}{g^2} + \frac{\theta}{2\pi}$, where $f_{one\ loop}(t)$ does not violate the s (dilaton–axion) Peccei–Quinn symmetry and the non perturbative part gives the space time instanton contribution. The generalization of this formula for $G = SU(N)$ is straightforward [4]. Moreover, the metric of the moduli space will be that of special geometry [6,8] .

Unlike the rigid case discussed in [3], it is natural to conjecture here a monodromy in two variables and a central charge of the type [3,11]

$$Z = \sum_{A=1}^3 N_{(m)}^A F_A - M_{(e)}^A X_A \quad (40)$$

where $A = 0, s, t$. The new 0, s components correspond to gravitationally electrically and magnetically charged states. This formula is analogous to the one suggested in [11] for the massive Kaluza-Klein and winding states for $(2, 2)$ supersymmetric compactifications. There, (X^A, F_A) play the rôle of periods of holomorphic three-form and duality is manifest with respect to monodromy in the moduli space of $(2, 2)$ vacua [6,8].

In this case the monodromy group, *i.e.* the duality group, would not be in $Sp(2, \mathbb{Z})$ but rather in $Sp(6, \mathbb{Z})$ with a Picard–Fuchs system identical in form to the two–parameter case of a Calabi–Yau moduli space. In this case there is an intriguing

analogy between the moduli space of $N = 2$ supersymmetric Yang–Mills theory coupled to supergravity (with gauge group G of rank r) and Calabi–Yau moduli space for the three-form cohomology with hodge number $h_{21} = r + 1$. The modular forms with respect to Γ should reconstruct the full holomorphic function $F(s, t)$. We further remark that the $Sl(2, \mathbb{Z})$ symmetry associated to dilaton–axion (S) duality is peculiar of $N = 4$ theories only, because of the absence of quantum corrections. Indeed, for $N = 2$ supersymmetric theories, the monodromy group associated to the periods $(1, s, t, F_s, F_t, 2F - sF_s - tF_t)$ is expected to be a discrete group $\Gamma \in Sp(6, \mathbb{Z})$, which will not in any way be related to $Sl(2, \mathbb{Z})$ or any of its subgroups. It is merely a property of the tree-level uncorrected prepotential $F(s, t) = st^2$ to exhibit a non–linear $Sl(2, \mathbb{R})$ symmetry (containing $Sl(2, \mathbb{Z})$) previously found in $N = 4$ supergravity[12]. This is similar to the example of the one–parameter Calabi–Yau moduli space whose metric for large volume approaches the metric of $\frac{SU(1,1)}{U(1)}$ homogeneous space[13].

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